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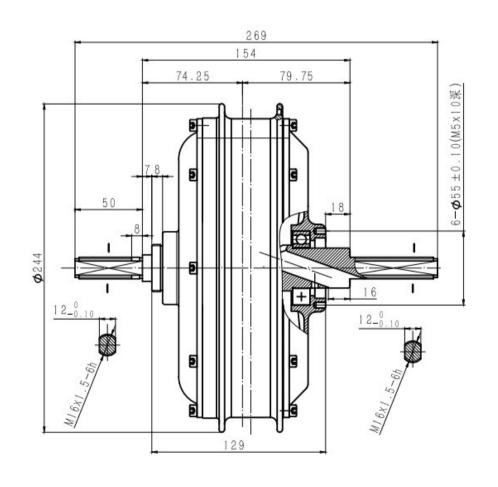
3000-5000 W

MECHANICAL PARAMETERS

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Nr.	Parameter	VALUE	Units	Notes	Picture
1	Motor model	QS-205 3000V	V / V	3 / H50 / 48-96V	
2	Motor type	3 phase Outer Roto	or BLDC	/ PMSM hub motor	
3	Axle Configuration	Doube Axle out		_	
4	Motor diameter	222	mm	_	
5	Spokes holes:	36 spokes		OD 4,2mm	
6				_	
7	Brake system	Bike Disc Brake		PCD 6*44mm, M5	
8				_	
9	Matching freewheel	Single Freewheel		Or 3 speed freewheel	
10	Matching Moto RIMs	16 - 21	Inch	Other on request	
11	Matching Bike RIMs	20 - 29	Inch	Other on request	
	Speed (depends on wheel size)		km/h	Optional 40-70 km/h	
12	Color	Black	-		
13	N.W. // G.W.	14 / 15	kg		A STATE OF THE PARTY OF THE PAR
14	Package	34*34*33	cm ³	Carton	

DRAWING:









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MOTOR SPECIFICATION:

Nr.	Basic parameters	Value	Units	Notes
1	Rated Power [kW]	3	kW	
2	Max Power [kW]	6	kW	Peak 20 kW in few sec
3	Rated Voltage [V]	48/60/72	V	Optional 96V
4	Rated Current [A]	67	A	•
5	Peak Input Current [A]	104	A	
6	Max Phase Current [A]	326	A	In short time
7	Max Current duration time [s]	10	Sec.	
8				
9	Number of Pole pairs	16	Pairs	32pcs.
10	Magnet Height	50	mm	
11	Max RPM	933	RPM	Depending on kV
12				Optional kV:
	kV (RPM per Volt)	9.0	RPM/V	6.0 / 9.0 / 13.0 / 14.9 / 18.0 / 19.4 etc.
13	Rated torque [N.m]	68	N.m.	
14	Max Torque [N.m]	189	N.m.	
15	Max Efficiency [%]	86-92	%	
16				
17	Phase Resistance [mΩ]		m Ω	Depending on Windings
18	Phase Induction [100 kHz]		uН	Depending on Windings
19				
20	Hall sensors	2	Set.	One for spare, Waterproof connector
21	Hall sensor electrical Angle	120	0	-
22	Hall working Voltage	5	V	
23	Temperature sensor	KTY83/122		Other type on request
24	Recomended working temperature	70 -120	°C	Peak 150°C; * 1 NOTE
25				
26	Waerproof Grade	54	IP	
27	Cooling type	AIR		Natural AIR cooling
28	Cross Section of Phase Wire	10	mm^2	not include insulation
				layer)

1 NOTE: Suggestion (Setting of Controller)

When it's 90 °C inside of motor (in 30s), the current should be limited 50%.

When it's 120 °C, the controller shut down. When it drop down to 70°C, the controller work again.



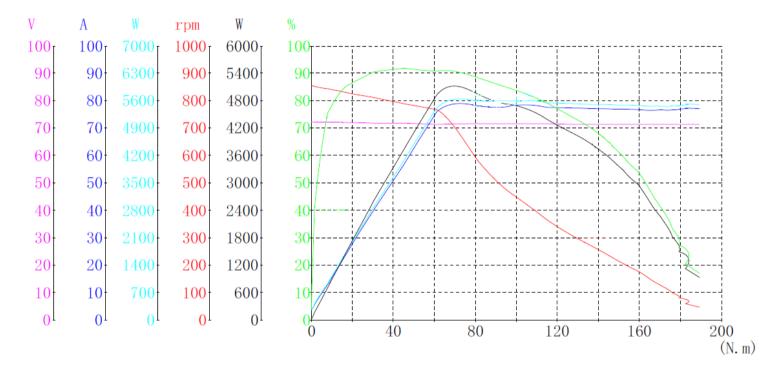


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QS-205 MOTOR TEST CURVE [30x4T]

Description	\mathbf{U}	Ι	P1	M	n	P2	EFF
	[V]	[A]	[W]	[N.m]	[RPM]	[W]	[%]
No Load	72.30	3.520	254.5	0.1	853.9	10.01	3.9
Max Eff	71.51	80.27	5 740	68.1	738.5	5 271	91.8
Max P out	70.51	80.27	5 740	68.1	738.5	5 271	91.8
Max Torque	70.30	77.08	5 497	189.2	46.9	929.3	16.9
End	70.30	77.08	5 497	189.2	46.9	929.3	16.9



Please note that the test curves can be done at different currents & Voltages. Therefore the torque and RPM can be different. However at respectively currents the torque at 72V and 96V will be the same or very similar.

The test curves at different motor windings and controller settings will be different. These curves only for general information.

Regarding Motor Supply Voltage / RPM and Power.

For example if motor is with windings 72V, this motor can also be run at lower voltages, such as 48V. The difference is that you wouldn't get as much power output since a lower voltage is associated a lower max attainable rpm. As power (W or Nm/s) is the product of angular speed (1/seconds) and torque (nm), with the same amount of torque and a lower rpm, you would have a lower power output.

You can achieve the same amount of torque at any voltage as torque is directly dependent on current. You may see something called a torque constant, such as Nm/A or ft-lbs/A. Simply multiply by the current, and you'll get the torque output before accounting for mechanical and electrical losses.

The main limiting factor on the amount of current you can pump into a motor is heat, which can melt the insulating varnish if too high.





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EXAMPLE OF CONVERSION with Single shaft motors

